

The chain rule, part 2
Math 131 Multivariate Calculus
D Joyce, Spring 2014

We'll continue the stages to a complete generalization of the chain rule that we started in part 1.

The second step where t becomes a vector \mathbf{t} . In general, we'll want \mathbf{t} to be a vector (t_1, t_2, \dots, t_n) , but, for purposes of illustration, let's make $n = 2$, and write $\mathbf{t} = (s, t)$. And, while we're at it, let's have $m = 2$ so that $\mathbf{x} = (x, y)$ where x and y are each functions of both s and t . Then $f \circ \mathbf{x} : \mathbf{R}^2 \rightarrow \mathbf{R}$ is defined by

$$(f \circ \mathbf{x})(\mathbf{t}) = f(x(s, t), y(s, t)).$$

We want to find $D(f \circ \mathbf{x})$ which comprises the two partial derivatives $\frac{\partial f}{\partial s}$ and $\frac{\partial f}{\partial t}$.

But these partials are each derivatives explained in the previous paragraphs. After all, a partial derivative is just an ordinary derivative when the other variables are left constant. So, we have

$$\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s}$$

and

$$\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t}.$$

When this is written out in matrix notation, we get the same matrix equation for the chain rule, namely,

$$D(f \circ \mathbf{x}) = Df D\mathbf{x},$$

the only difference is, this time the two matrices being multiplied together don't have one row and one column, but two, and in general they'll have n .

Example 1. We need an example to illustrate what's going on. Let $f(x, y) = \sqrt{x^2 + y^2}$, let $x(s, t) = s \ln t$, and let $y(s, t) = \sin s + \cos t$. Then

$$f(x(s, t), y(s, t)) = \sqrt{(s \ln t)^2 + (\sin s + \cos t)^2}.$$

Therefore,

$$\begin{aligned} \frac{df}{ds} &= \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s} \\ &= \frac{x}{\sqrt{x^2 + y^2}} \ln t + \frac{y}{\sqrt{x^2 + y^2}} \cos s \\ \frac{df}{dt} &= \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial t} \\ &= \frac{x}{\sqrt{x^2 + y^2}} \left(\frac{s}{t}\right) + \frac{y}{\sqrt{x^2 + y^2}} (-\sin t) \end{aligned}$$

The derivative of a composition is the product of matrices. We're up to the last step of generalizing the chain rule where f becomes a vector-valued function.

There really isn't much more to do when $\mathbf{f} = (f_1, f_2, \dots, f_p)$. That's because the derivative $D\mathbf{f}$ of the vector-valued function \mathbf{f} is just a matrix whose rows are the derivatives Df_j of the component functions f_j for $j = 1, 2, \dots, p$. Since each $D(f_j \circ \mathbf{x}) = Df_j D\mathbf{x}$, placing them in rows gives the matrix product

$$D(\mathbf{f} \circ \mathbf{x}) = D\mathbf{f} D\mathbf{x}$$

Note that \mathbf{f} is a function $\mathbf{R}^m \rightarrow \mathbf{R}^p$ while its derivative $D\mathbf{f}$ is a $p \times m$ matrix; also \mathbf{x} is a function $\mathbf{R}^n \rightarrow \mathbf{R}^m$ while its derivative $D\mathbf{x}$ is an $m \times n$ matrix; so the composition $\mathbf{f} \circ \mathbf{x}$ is a function $\mathbf{R}^n \rightarrow \mathbf{R}^p$ and its derivative $D(\mathbf{f} \circ \mathbf{x})$ is a $p \times n$ matrix.

Polar/rectangular conversions. We now know that the chain rule is, in general, a product of matrices

$$D(\mathbf{f} \circ \mathbf{x}) = D\mathbf{f} D\mathbf{x}.$$

As an important application of this general chain rule, we'll develop the derivatives associated to polar/rectangular conversions.

Suppose $f : \mathbf{R}^2 \rightarrow \mathbf{R}$ is a scalar-valued function defined on the plane. Let's use the notation $w = f(x, y)$. Then we have the two partial derivatives $\frac{\partial w}{\partial x}$ and $\frac{\partial w}{\partial y}$ as usual. But sometimes we want to use polar coordinates and find the partials with respect to r and θ . Of course, we could figure them out directly since we know how to express f in terms of r and θ , since $w = f(x, y) = f(x(r, \theta), y(r, \theta))$ where $x(r, \theta) = r \cos \theta$ and $y(r, \theta) = r \sin \theta$. Here the question is: can we figure out what $\frac{\partial w}{\partial r}$ and $\frac{\partial w}{\partial \theta}$ are directly from $\frac{\partial w}{\partial x}$ and $\frac{\partial w}{\partial y}$?

We can treat the vector $\mathbf{x} = (x, y)$ as a function $\mathbf{R}^2 \rightarrow \mathbf{R}^2$ as

$$\mathbf{x}(r, \theta) = (x(r, \theta), y(r, \theta)) = (r \cos \theta, r \sin \theta).$$

Then we can apply the general chain rule $D(\mathbf{f} \circ \mathbf{x}) = D\mathbf{f} D\mathbf{x}$. We'll get the matrix equation

$$\begin{aligned} \begin{bmatrix} \frac{\partial w}{\partial r} & \frac{\partial w}{\partial \theta} \end{bmatrix} &= \begin{bmatrix} \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} \end{bmatrix} \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} \end{bmatrix} \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix} \end{aligned}$$

This result is usually summarized in terms of differential operators where the name of the function being differentiated is omitted.

$$\begin{aligned} \frac{\partial}{\partial r} &= \cos \theta \frac{\partial}{\partial x} + \sin \theta \frac{\partial}{\partial y} \\ \frac{\partial}{\partial \theta} &= -r \sin \theta \frac{\partial}{\partial x} + r \cos \theta \frac{\partial}{\partial y} \end{aligned}$$

Conversely, you can find the partials with respect to x and y in terms of those for r and θ .

$$\begin{aligned} \frac{\partial}{\partial x} &= \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \\ \frac{\partial}{\partial y} &= \sin \theta \frac{\partial}{\partial r} + \frac{\cos \theta}{r} \frac{\partial}{\partial \theta} \end{aligned}$$

Math 131 Home Page at

<http://math.clarku.edu/~djoyce/ma131/>